

Lecture 5: Calculus of Variations II

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Disclaimer: Zhikun is fully responsible for the errors and typos appeared in the notes.

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5.1 Continue in Continuous Time

Back to the example at beginning of this course (in Section 1.2):

$$\begin{cases} \min & \int_0^T \{c_1(x'(t))^2 + c_2x(t)\}dt \\ \text{s.t.} & x(0) = 0, x(T) = B, x'(t) \geq 0 \end{cases} \quad (5.1)$$

$$F_x = c_2, \quad F_{x'} = 2c_1x'(t), \quad \frac{dF_{x'}}{dt} = 2c_1x''(t)$$

$$\frac{dF_{x'}}{dt} = F_x \implies 2c_1x''(t) = c_2$$

$$x(t) = \frac{c_2}{4c_1}t^2 + k_1t + k_2$$

$$x(0) = k_2 = 0, \quad x(T) = \frac{c_2}{4c_1}T^2 + k_1T = B$$

\implies

$$k_1 = \frac{B}{T} - \frac{c_2T}{4c_1} \quad (5.2)$$

$$x^*(t) = \frac{c_2}{4c_1}t^2 + \left(\frac{B}{T} - \frac{c_2T}{4c_1}\right)t \quad (5.3)$$

Interpreting the Euler equation

$$c_1(x'(t))^2 = \text{Marginal cost of production} \quad (5.4)$$

$$2c_1x''(t) = \text{Rate of change in marginal cost} \quad (5.5)$$

$$c_2 = \text{unit inventory holding cost} \quad (5.6)$$

$$\text{Euler Equation : } 2c_1x''(t) = c_2 \quad (5.7)$$

Another look

$$\int_t^{t+\Delta} 2c_1x''(s)ds = \int_t^{t+\Delta} c_2ds \quad (5.8)$$

¹Visit <http://www.luzk.net/misc> for updates.

$$\begin{aligned}
2c_1[x'(t + \Delta) - x'(t)] &= c_2\Delta \\
\iff 2 \underbrace{c_1 x'(t)}_{(a)} + c_2\Delta &= 2 \underbrace{c_1 x'(t + \Delta)}_{(b)}
\end{aligned} \tag{5.9}$$

which means that in optimum, we should be indifferent between

- (a) producing a unit now (at time t) and storing it for Δ amount of time and
 (b) producing a unit at time $t + \Delta$

Brachistchrone Challenge

$$\begin{aligned}
T &= \int dt = \text{Total travel time} \\
dt &= \frac{ds}{ds/dt} = \frac{ds}{v}
\end{aligned}$$

where ds is a "short" distance travelled.

$$\begin{aligned}
(ds)^2 &= (dx)^2 + (dy)^2 \\
\frac{ds}{dx} &= \sqrt{1 + \underbrace{\left(\frac{dy}{dx}\right)^2}_{y'(x)}} \\
ds &= \sqrt{1 + y'^2} dx
\end{aligned}$$

Assumption

$$\underbrace{\frac{mv^2}{2}}_{\text{Kinetic energy}} = \underbrace{mgy}_{\text{Potential energy}} \tag{5.10}$$

$$m = \text{mass} \tag{5.11}$$

$$g = \text{gravity acceleration parameter} \tag{5.12}$$

$$mg = \text{weight} \tag{5.13}$$

$$\implies v = \sqrt{2gy} \tag{5.14}$$

$$\begin{aligned}
\min \int_{x_1}^{x_2} dt &= \int_{x_1}^{x_2} \frac{ds}{v} = \int_{x_1}^{x_2} \frac{\sqrt{1 + y'^2}}{\sqrt{2gy}} dx \\
&= \frac{1}{\sqrt{2g}} \int_{x_1}^{x_2} \frac{\sqrt{1 + y'(x)^2}}{\sqrt{y(x)}} dx \\
&\iff \min \int_{x_1}^{x_2} \frac{\sqrt{1 + y'(x)^2}}{\sqrt{y(x)}} dx
\end{aligned} \tag{5.15}$$

FONC (other version of the EE, see equation(4.27)):

$$\frac{d(F - y'F_{y'})}{dx} = F_t = 0$$

Note that the second equal sign above is not necessarily true in general. This is true in our case.

$$\left[\frac{1 + (y'(x))^2}{y(x)} \right]^{1/2} - (y'(x))^2 [(1 + (y'(x))^2)y(x)]^{-1/2} = C \tag{5.16}$$

Solution to this differential equation is given by

$$x = -(2ky - y^2)^{\frac{1}{2}} + k \arccos\left(1 - \frac{y}{k}\right) + \bar{k} \quad (5.17)$$

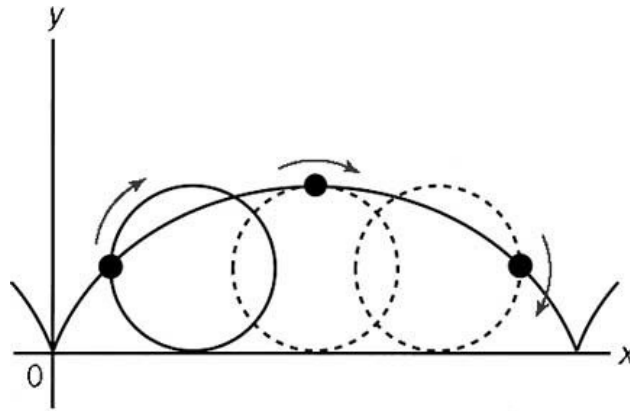


Figure 5.1: the solution is a cycloid (picture from the Internet)

Notes

1. If we have n choice variables, then we need to write EE for each one of them.
2. In case of higher order derivatives, we can proceed either by
 - a) introducing new variable, or
 - b) using Euler-Poisson Equation.

Example:

$$\int_0^T (ty^2 + yy' + y'^2) dt \quad (5.18)$$

$$y(0) = A, \quad y(T) = B, \quad y'(0) = \alpha, \quad y'(T) = \beta$$

Let: $z = y' \implies z' = y''$

\implies

$$F = ty^2 + yz + z'^2, \quad z(0) = \alpha, \quad z(T) = \beta$$

\implies

$$\begin{cases} \int_0^T ty^2 + yz + z'^2 dt \\ y(0) = A, \quad y(T) = B, \quad z(0) = \alpha, \quad z(T) = \beta \end{cases} \quad (5.19)$$

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Example: Continuous Time Dynamic Optimization Model

$$\max \int_0^{\infty} U(C(t))e^{-\delta t} dt \quad (5.20)$$

$$\text{s.t. } C(t) + B'(t) = \rho(t)B(t) + Y(t) \quad (5.21)$$

where

C = consumption

Y = income

B = Bonds/Saving

$\rho(t)$ = Time-varying interest rate

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General Constrained Case

$$\max \int_0^{\infty} F(y(t), y'(t), t) dt \quad (5.22)$$

$$\text{s.t. } G(y(t), y'(t), t) = 0, \forall t \quad (5.23)$$

The Lagrangian is given by

$$\mathcal{L} = \int_0^{\infty} F(y(t), y'(t), t) + \lambda(t)G(y(t), y'(t), t) dt.$$

Euler Equation:

$$\frac{\partial F}{\partial y(t)} + \lambda(t) \frac{\partial G}{\partial y(t)} - \frac{d}{dt} \left[\frac{\partial F}{\partial y'(t)} + \lambda(t) \frac{\partial G}{\partial y'(t)} \right] = 0 \quad (5.24)$$

EE w.r.t. $C(t)$:

$$U'(C(t))e^{-\delta t} + \lambda(t) = 0 \quad (5.25)$$

$$\implies U'(C(t))e^{-\delta t} = -\lambda(t) \quad (5.26)$$

EE w.r.t. $B(t)$:

$$\lambda(t)(-\rho(t)) - \frac{d}{dt}[\lambda(t)] = 0 \quad (5.27)$$

$$\implies -\lambda(t)\rho(t) = \lambda'(t) \quad (5.28)$$

(5.26) \implies

$$\ln U'(C(t)) - \delta t = \ln(-\lambda(t))$$

\implies

$$\frac{1}{U'(C(t))} U''(C(t)) C'(t) - \delta = \frac{-\lambda'(t)}{-\lambda(t)} = -\rho(t)$$

\implies

$$-\frac{U''(C(t))}{U'(C(t))} C'(t) = \rho(t) - \delta \quad (5.29)$$

Two equations: (5.21) and (5.29)

Two unknowns: $\{C_t\}_{t=0}^{\infty}$, $\{B_t\}_{t=0}^{\infty}$

$$(5.21) \iff B'(t) - \rho(t)B(t) = Y(t) - C(t) \quad (5.30)$$

Recall

$$y'(t) + g(t)y(t) = h(t) \quad (5.31)$$

Forward-looking solution

$$y(t) = Ae^{-\int_0^t g(v)dv} - e^{-\int_0^t g(v)dv} \int_t^{\infty} h(s)e^{\int_t^{t+s} g(v)dv} ds \quad (5.32)$$

Claim: $e^{-\int_0^t \rho(s) ds} = \Phi(t)$ is the discount factor when $\rho = \rho(t)$.

If $\rho(t) = \rho$, $\Phi(t) = e^{-\rho t}$.

$$B(t) = A \underbrace{e^{\int_0^t \rho(v) dv}}_{[\Phi(t)]^{-1}} - e^{\int_0^t \rho(v) dv} \int_t^\infty [Y(s) - C(s)] e^{-\int_t^{t+s} \rho(v) dv} ds \quad (5.33)$$

Assumption

- $\rho(t) = \rho \implies e^{\int_0^t \rho dv} = e^{\rho t} = [\Phi(t)]^{-1}$
- $Y(t) = Y$ (a constant)

$$B(t) = A[\Phi(t)]^{-1} - [\Phi(t)]^{-1} \int_t^\infty \Phi(s)[Y - C(s)] ds \quad (5.34)$$

$$B(t) = Ae^{\rho t} - e^{\rho t} \int_t^\infty e^{-\rho s} [Y - C(s)] ds \quad (5.35)$$

$$e^{\rho t} \int_t^\infty e^{-\rho s} C(s) ds = B(t) + e^{\rho t} \int_t^\infty e^{-\rho s} Y ds - Ae^{\rho t} \quad (5.36)$$

If $A > 0$, PDV of C shrinks exponentially.

If $A < 0$, PDV of C grows exponentially.

$\implies A = 0$

$$\underbrace{e^{\rho t} \int_t^\infty e^{-\rho s} C(s) ds}_{\text{life-time budget constraint}} = B(t) + e^{\rho t} \int_t^\infty e^{-\rho s} Y ds \quad (5.37)$$

Assumption

- CRRA type utility function $U(C) = \ln C$

$$(5.29) \implies \left(-\frac{U''}{U'} C \right) \frac{C'}{C} = \rho - \delta,$$

where $-\frac{U''}{U'} C$ is the coefficient of relative risk aversion.

\implies

$$\frac{C'(t)}{C(t)} = \rho - \delta \quad (5.38)$$

\implies

$$C(t) = e^{(\rho - \delta)t + a} \quad (5.39)$$

$$C(s) = e^{(\rho - \delta)(s - t)} C(t) \quad (5.40)$$

(5.37) \implies

$$e^{\rho t} \int_t^\infty e^{-\rho s} e^{(\rho-\delta)(s-t)} C(t) ds = e^{\rho t} \int_t^\infty e^{-\rho s} Y ds + B(t) \quad (5.41)$$

$$C(t) e^{\rho t} \int_t^\infty e^{-\rho s} e^{(\rho-\delta)(s-t)} ds = e^{\rho t} Y \int_t^\infty e^{-\rho s} ds + B(t) \quad (5.42)$$

$$C(t) e^{\rho t} e^{\delta t - \rho t} \int_t^\infty e^{-\delta s} ds = Y e^{\rho t} \int_t^\infty e^{-\rho s} ds + B(t) \quad (5.43)$$

$$C(t) e^{\delta t} \int_t^\infty e^{-\delta s} ds = Y e^{\rho t} \int_t^\infty e^{-\rho s} ds + B(t) \quad (5.44)$$

$$C(t) e^{\delta t} \left(\frac{e^{-\delta t}}{\delta} \right) = Y e^{\rho t} \left(\frac{e^{-\rho t}}{\rho} \right) + B(t) \quad (5.45)$$

$$\frac{C(t)}{\delta} = \frac{Y}{\rho} + B(t) \quad (5.46)$$

$$C(t) = \underbrace{\frac{\delta}{\rho}}_{MPC} [Y + \rho B(t)] \quad (5.47)$$

Backward-looking solution (applies when $g(t) > 0$)

$$y(t) = A e^{-\int_0^t g(v) dv} + \int_0^\infty h(t-s) e^{\int_t^{t-s} g(v) dv} ds \quad (5.48)$$

5.2 Discrete time

$$P_t = \alpha P_{t-1} + \beta$$

$$P_0 = \text{given}$$

$$P_1 = \alpha P_0 + \beta$$

$$P_2 = \alpha^2 P_0 + \alpha \beta + \beta$$

$$P_3 = \alpha^3 P_0 + \alpha^2 \beta + \alpha \beta + \beta$$

$$\vdots$$

$$P_t = \alpha^t P_0 + \sum_{i=0}^{t-1} \alpha^i \beta = \alpha^t P_0 + \frac{\beta}{1-\alpha} - \frac{\beta}{1-\alpha} \alpha^t$$

$$P_t = \frac{\beta}{1-\alpha} + (P_0 - \frac{\beta}{1-\alpha}) \alpha^t$$

If $P_0 = \underbrace{\frac{\beta}{1-\alpha}}_{P^*}$, then $P_t = \frac{\beta}{1-\alpha}$ for all t .

[insert two graphs here for the convergence patterns of $0 < \alpha < 1$ and $-1 < \alpha < 0$]

$|\alpha| < 1$ – stable root

$|\alpha| > 1$ – unstable root

Lag Operator (Sargent (1987))

$$Lx_t = x_{t-1} \quad (5.49)$$

$$L(Lx_t) = L^2x_t = x_{t-2} \quad (5.50)$$

$$L^n x_t = x_{t-n} \quad (5.51)$$

$$L^{-1}x_t = x_{t+1} \quad (5.52)$$

$$L^{-n}x_t = x_{t+n} \quad (5.53)$$

$$L^0 \equiv 1 \quad (5.54)$$

Polynomial of Lag Operator

$$A(L) = a_0 + a_1L + a_2L^2 + \dots = \sum_{j=0}^{\infty} a_jL^j \quad (5.55)$$

$$\begin{aligned} A(L)x_t &= (a_0 + a_1L + a_2L^2 + \dots)x_t \\ &= a_0x_t + a_1x_{t-1} + a_2x_{t-2} + \dots \\ &= \sum_{j=0}^{\infty} a_jx_{t-j} \end{aligned} \quad (5.56)$$

Rational Polynomial

$$A(L) = \frac{B(L)}{C(L)} \quad (5.57)$$

Example:

$$AL = \frac{1}{1 - \lambda L}$$

Claim: If $|\lambda| < 1$, then

$$\frac{1}{1 - \lambda L} = 1 + \lambda L + \lambda^2 L^2 + \dots = \sum_{i=0}^{\infty} \lambda^i L^i \quad (5.58)$$

If $|\lambda| > 1$, then

$$\frac{1}{1 - \lambda L} = 1 + \frac{\lambda L}{1 - \lambda L} = 1 - \frac{1}{1 - (\frac{1}{\lambda})L^{-1}} = 1 - \left(1 + \frac{1}{\lambda}L^{-1} + \left(\frac{1}{\lambda}\right)^2 L^{-2} + \dots\right) = -\sum_{i=1}^{\infty} \left(\frac{1}{\lambda}\right)^i L^{-i} \quad (5.59)$$

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References