

Lecture 4: Calculus of Variations

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4.1 The simplest problem of Calculus of Variations

$$\max_{x(t)} \int_{t_1}^{t_2} F(t, x(t), x'(t)) dt \quad (4.1)$$

$$\text{s.t. } x(t_0) = x_0, x(t_1) = x_1 \quad (4.2)$$

Assumptions

1. $F(\dots)$ is continuous in its three arguments.
2. $F(\dots)$ has continuous partial derivatives w.r.t. $x(t)$ and $x'(t)$.

Definition 4.1 A path is feasible or admissible if it is C^1 on $[t_0, t_1]$ and satisfies (4.2).

FONC (Euler Equation)

Suppose that $x^*(t)$, $t_0 \leq t \leq t_1$ solves (4.1). Let $x(t)$ be some other feasible path. Let $h(t)$ be:

$$h(t) = x(t) - x^*(t) \quad (4.3)$$

Thus:

- $x(t)$ is a comparision path.
- $h(t)$ is a deviation path.

Since $x(t)$ and $x^*(t)$ both satisfy (4.2), we have

$$h(t_0) = h(t_1) = 0 \quad (4.4)$$

Define $y(t)$ as follows

$$y(t) = x^*(t) + ah(t) \quad (4.5)$$

where a is some parameter.

Then

$$\begin{cases} y(t_0) = x^*(t_0) + ah(t_0) = x^*(t_0) = x_0 \\ y(t_1) = x^*(t_1) + ah(t_1) = x^*(t_1) = x_1 \end{cases} \quad (4.6)$$

It follows that $y(t)$ is a feasible path because it is C^1 for any arbitrary a and it satisfies (4.2).

¹Visit <http://www.luzk.net/misc> for updates.

[insert a graph of $[x^*(t), x(t), h(t)]$ here]

Hold $x^*(t)$ and $h(t)$ fixed and compute (4.1) for $y(t)$ as a function of a :

$$\begin{aligned}
 g(a) &\stackrel{\text{def}}{=} \int_{t_0}^{t_1} F(t, y(t), y'(t)) dt \\
 &= \int_{t_0}^{t_1} F(t, x^*(t) + ah(t), x^{*'}(t) + ah'(t)) dt
 \end{aligned}
 \tag{4.7}$$

By assumption $x^*(t)$ maximizes (4.1). Therefore the function $g(a)$ will attain its maximum where $a = 0$. Therefore, by regular FONC,

$$g'(a) \Big|_{a=0} = g'(0) = 0
 \tag{4.8}$$

Leibnitz Theorem

Let $f(x, r)$ be continuous w.r.t. x , $\forall r$, and let $\frac{\partial f(x, r)}{\partial r}$ be continuous in the rectangle $a \leq x \leq b$, $\underline{r} \leq r \leq \bar{r}$ in the x - r plane. Let the functions $A(r)$ and $B(r)$ be C^1 . If $V(r) = \int_{A(r)}^{B(r)} f(x, r) dx$, then

$$V'(r) = f(B(r), r)B'(r) - f(A(r), r)A'(r) + \int_{A(r)}^{B(r)} \frac{\partial f(x, r)}{\partial r} dx
 \tag{4.9}$$

By Leibnitz Theorem

$$\begin{aligned}
 g'(a) &= F(t, x^*(t_1(a)) + ah(t_1(a)), x^{*'}(t_1(a)) + ah'(t_1(a))) \left(\frac{dt_1}{da} \right) \\
 &\quad - F(t, x^*(t_0(a)) + ah(t_0(a)), x^{*'}(t_0(a)) + ah'(t_0(a))) \left(\frac{dt_0}{da} \right) \\
 &\quad + \int_{t_0}^{t_1} \left[F_x(t, x^*(t) + ah(t), x^{*'}(t) + ah'(t))h(t) \right. \\
 &\quad \left. + F_{x'}(t, x^*(t) + ah(t), x^{*'}(t) + ah'(t))h'(t) \right] dt \\
 &= \int_{t_0}^{t_1} \left[F_x(t, x^*(t) + ah(t), x^{*'}(t) + ah'(t))h(t) + F_{x'}(t, x^*(t) + ah(t), x^{*'}(t) + ah'(t))h'(t) \right] dt
 \end{aligned}
 \tag{4.10}$$

$$g'(0) = \int_{t_0}^{t_1} \left[F_x(t, x^*(t), x^{*'}(t))h(t) + F_{x'}(t, x^*(t), x^{*'}(t))h'(t) \right] dt = 0 \quad \text{by FONC}
 \tag{4.11}$$

which is a necessary condition for a maximum.

Note: (4.11) must hold for all h that is continuous and satisfies (4.4).

Recall: Integration by part

$$\begin{aligned}
 \int_{t_0}^{t_1} \left[F_{x'}(t, x^*(t), x^{*'}(t))h'(t) \right] dt &= \left[F_{x'}(t, x^*(t), x^{*'}(t))h(t) \right]_{t_0}^{t_1} - \int_{t_0}^{t_1} \left[h(t) \frac{d}{dt} F_{x'}(t, x^*(t), x^{*'}(t)) \right] dt \\
 &= 0 - \int_{t_0}^{t_1} \left[h(t) \frac{d}{dt} F_{x'}(t, x^*(t), x^{*'}(t)) \right] dt
 \end{aligned}
 \tag{4.13}$$

$$g'(0) = \int_{t_0}^{t_1} \left[F_x(t, x^*(t), x^{*'}(t))h(t) + F_{x'}(t, x^*(t), x^{*'}(t))h'(t) \right] dt \quad (4.14)$$

$$= \int_{t_0}^{t_1} \left[F_x(t, x^*(t), x^{*'}(t))h(t) \right] dt + \int_{t_0}^{t_1} \left[F_{x'}(t, x^*(t), x^{*'}(t))h'(t) \right] dt \quad (4.15)$$

$$= \int_{t_0}^{t_1} \left[F_x(t, x^*(t), x^{*'}(t))h(t) \right] dt - \int_{t_0}^{t_1} \left[h(t) \frac{d}{dt} F_{x'}(t, x^*(t), x^{*'}(t)) \right] dt \quad (4.16)$$

$$= \int_{t_0}^{t_1} \left[F_x(t, x^*(t), x^{*'}(t)) - \frac{d}{dt} F_{x'}(t, x^*(t), x^{*'}(t)) \right] h(t) dt = 0 \quad (4.17)$$

(4.17) must hold true if $x^*(t)$ maximizing (4.1). Moreover, it must hold for all $h(t)$ that is C^1 and satisfies (4.4). This will be true only if the term in the brackets vanishes:

$$F_x - \frac{d}{dt} F_{x'} = 0, \quad t_0 \leq t \leq t_1 \quad (4.18)$$

which is a necessary condition for a maximum. (4.18) is called Euler Equation. The Euler equation holds true because of the following lemma.

Theorem 4.2 (The Fundamental Lemma of Calculus of Variations) *Suppose that $g(t)$ is a continuous function defined on $[t_0, t_1]$. If*

$$\int_{t_0}^{t_1} g(t)h(t)dt = 0 \quad (4.19)$$

for all continuous $h(t)$ defined on $[t_0, t_1]$ and satisfies (4.4), then $g(t) = 0 \quad \forall t \in [t_0, t_1]$.

Proof: Suppose that $g(t) \neq 0$ for some $\bar{t} \in [t_0, t_1]$. WLOG, assume $g(\bar{t}) = m > 0$. Since $g(t)$ is continuous at $t = \bar{t}$, for $\epsilon = \frac{m}{2}$, we know there exist $\delta_\epsilon > 0$ such that,

$$g(t) \geq g(\bar{t}) - \epsilon = m - \frac{m}{2} = \frac{m}{2}, \quad \forall t \in (\bar{t} - \delta_\epsilon, \bar{t} + \delta_\epsilon) \cap [t_0, t_1] \quad (4.20)$$

Let $h(t)$ be

$$h(t) = \begin{cases} (t-a)(b-t), & \text{if } t \in [a, b] \\ 0, & \text{elsewhere} \end{cases} \quad (4.21)$$

with $a = \max\{\bar{t} - \delta_\epsilon, t_0\}$, $b = \min\{\bar{t} + \delta_\epsilon, t_1\}$, and $b - a > 0$ for δ_ϵ sufficiently small. (Also note that $h(t_0) = h(t_1) = 0$ and $h(\cdot)$ is continuous.)

$$\int_{t_0}^{t_1} g(t)h(t)dt = \int_a^b g(t)(t-a)(b-t)dt \geq \int_a^b \frac{m}{2}(t-a)(b-t)dt = \frac{(b-a)^3}{6} > 0 \quad (4.22)$$

which contradicts the hypothesis that (4.19) holds for all $h(t)$ with the required properties. ■

Other versions of the Euler equation

$$\frac{dF_{x'}}{dt} = F_{x't} + F_{x'x}x' + F_{x'x'}x'' \quad (4.23)$$

$$\implies F_x = F_{x't} + F_{x'x}x' + F_{x'x'}x'' \quad (4.24)$$

where the partial derivatives must be evaluated at $(t, x^*, x^{*\prime})$ and $x' = x'(t)$, $x'' = x''(t)$. Note also that (4.24) is a second order differential equation.

Integrate (4.18) \implies

$$F_{x'} = \int F_x + C_1 \quad (4.25)$$

which is known as du Bois-Reymond equation.

Consider

$$\frac{d}{dt}[F - x'F_{x'}] = F_t + F_x x' + \cancel{F_{x'} x''} - x' \frac{dF_{x'}}{dt} - \cancel{x'' F_{x'}} = F_t + x' \left(\cancel{F_x} - \frac{dF_{x'}}{dt} \right) \stackrel{0 \text{ by EE}}{\quad} \quad (4.26)$$

\implies

$$\frac{d}{dt}[F - x'F_{x'}] = F_t \quad (4.27)$$

which is particularly useful if F does not depend on t directly, i.e. $F_t = 0$.

Example: $F(\cdot) = (x'(t))^2$

$$\begin{cases} \min & \int_0^T (x'(t))^2 dt \\ \text{s.t.} & x(0) = 0, x(T) = B \end{cases} \quad (4.28)$$

■

$$F_{x'} = 2x'(t), F_x = 0 \quad (4.29)$$

EE \implies

$$0 = \frac{d}{dt}[2x'(t)] \quad (4.30)$$

$$\implies x''(t) = 0 \quad (4.31)$$

$$x(t) = c_1 t + c_2 \quad (4.32)$$

With $x(0) = 0$, $x(T) = B$, we get

$$x(t) = \frac{B}{T}t. \quad (4.33)$$

References